# Programming Languages: Imperative Program Construction 8. Case Studies

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# **1** Faster Division

# **Quotient and Remainder**

• Recall the problem:

 $\begin{array}{l} \mathbf{con} \ A,B: Int \ \{ 0 \leqslant A \land 0 < B \} \\ \mathbf{var} \ q,r: Int \\ ? \\ \{ A = q \times B + r \land 0 \leqslant r < B \} \end{array}.$ 

- Recall: recognising the postcondition as a conjunction, we use  $A = q \times B + r \land 0 \leq r$  as the invariant and  $\neg (r < B)$  as the guard.
- The program we came up with:

$$\begin{array}{l} q,r:=0,A\\ \{A=q\times B+r\wedge 0\leqslant r,bnd:r\}\\ \mathbf{do}\ B\leqslant r\rightarrow q:=q+1\\ r:=r-B\\ \mathbf{od}\\ \{A=q\times B+r\wedge 0\leqslant r< B\} \end{array}.$$

- In each iteration of the loop, r is decreased by B.
- We can probably get a quicker program by decreasing r by ...  $2 \times B$ , when possible.
- What about decreasing r by  $4 \times B$ ,  $8 \times B$ ,... etc?

# **1.1** Division in $O(\log(A/B))$ Time

Strategy...

 $\begin{array}{l} \mathbf{con} \ A,B: Int \ \{0 \leqslant A \land 0 < B\} \\ \mathbf{var} \ q,r,b,k: Int \\ \dots \\ \{0 \leqslant k \land b = 2^k \times B \land A < b\} \\ \dots \\ \{A = q \times b + r \land 0 \leqslant r < b \land \\ 0 \leqslant k \land b = 2^k \times B, bnd: b\} \\ \mathbf{do} \ b \neq B \rightarrow \dots \mathbf{od} \\ \{A = q \times B + r \land 0 \leqslant r < B\} \end{array}$ 

# **Generating** $2^k \times B$

• It is easy to satisfy  $b = 2^k \times B \land A < b$ .

 $\begin{array}{l} b,k := B,0\\ \mathbf{do} \ b \leqslant A \rightarrow b,k := b \times 2, k+1 \ \mathbf{od}\\ \{ 0 \leqslant k \wedge b = 2^k \times B \wedge A < b \} \end{array}$ 

- What are the loop invariant and the bound?
- · Initialisation for the next loop easily follows:

$$\begin{aligned} \{ 0 \leqslant k \land b = 2^k \times B \land A < b \} \\ q, r := 0, A \\ \{ A = q \times b + r \land 0 \leqslant r < b \land \\ 0 \leqslant k \land b = 2^k \times B \} \end{aligned}$$

# Decreasing b

• What needs to be done before we decrement *b* by half?

$$(A = q \times b + r \land 0 \leqslant r < b)[b \backslash b / 2] \equiv (A = q \times (b / 2) + r \land 0 \leqslant r < b / 2)$$

• We can restore the invariant by  $q := q \times 2$ ...

$$(A = q \times (b / 2) + r \land 0 \leq r < b / 2)[q \setminus q \times 2]$$
  
$$\equiv A = (q \times 2) \times (b / 2) + r \land 0 \leq r < b / 2$$
  
$$\Leftrightarrow A = q \times b + r \land 0 \leq r < b / 2 \land b = 2^k \times B$$

- only if we already have r < b / 2!
- · That gives us one guarded command:

$$r < b / 2 \rightarrow q, b, k := q \times 2, b / 2, k - 1$$

# **Decreasing** b – The Other Case

- What about the case when  $b / 2 \leq r < b$ ?
- The task is to find a substitution such that

$$(A = q \times (b / 2) + r \land 0 \leq r < b / 2)[? \land ?]$$
  
$$\Leftarrow A = q \times b + r \land b / 2 \leq r < b \land b = 2^k \times B$$

• Comparing  $0 \le r < b/2$  and  $b/2 \le r < b$ , one might want to try a substitution containing  $[r \setminus r - b / 2]$ .

$$\begin{array}{l} (0 \leqslant r < b / 2)[r \backslash r - b / 2] \\ \equiv 0 \leqslant r - b / 2 < b / 2 \\ \Leftarrow b / 2 \leqslant r < b \land b = 2^k \times B \end{array} .$$

• Consider the former half of the expression:

$$(A = q \times (b / 2) + r)[r \setminus r - b / 2]$$
  
$$\equiv A = q \times (b / 2) + r - b / 2$$
  
$$\equiv A = (q - 1) \times (b / 2) + r .$$

- Applying  $[q \setminus q \times 2 + 1]$  gives us back  $A = q \times b + r$ .
- Therefore, another guarded command:

$$\begin{array}{l} b \ / \ 2 \leqslant r \rightarrow q, b, k, r := \\ q \times 2 + 1, b \ / \ 2, k - 1, r - b \ / \ 2 \end{array}$$

**The Program** 

 $\begin{array}{l} \mathbf{con}\ A,B:Int\ \{0\leqslant A\wedge 0< B\}\\ \mathbf{var}\ q,r,b,k:Int\\ b,k:=B,0\\ \mathbf{do}\ b\leqslant A\rightarrow b,k:=b\times 2,k+1\ \mathbf{od}\\ \{0\leqslant k\wedge b=2^k\times B\wedge A< b\}\\ q,r:=0,A\\ \{A=q\times b+r\wedge 0\leqslant r< b\wedge\\ 0\leqslant k\wedge b=2^k\times B,bnd:b\}\\ \mathbf{do}\ b\neq B\rightarrow\\ \mathbf{if}\ r< b/2\rightarrow q,b,k:=q\times 2,b/2,k-1\\ \mid\ b/2\leqslant r\rightarrow q,b,k,r:=q\times 2+1,b/2,\\ k-1,r-b/2\\ \mathbf{fi}\\ \mathbf{od}\\ \{A=q\times B+r\wedge 0\leqslant r< B\}\end{array}$ 

# 1.2 Alternative Programs

# **Existential Quantification**

- The variable *k* is used in the proofs, but not needed for computing the output.
- Such a variable is called a "ghost variable" in Kaldewaij [Kal90].
- One can remove k, and the program would still work.
- For its reasoning, we need to use existential quantification in the assertions to talk about properties involving *k*.

$$\begin{array}{l} \operatorname{con} A,B: Int \ \{0 \leqslant A \land 0 < B\} \\ \operatorname{var} q,r,b: Int \\ b:=B \\ \operatorname{do} b \leqslant A \rightarrow b:=b \times 2 \operatorname{od} \\ \{\langle \exists k: 0 \leqslant k: b = 2^k \times B \rangle \land A < b\} \\ q,r:=0,A \\ \{A = q \times b + r \land 0 \leqslant r < b \land \\ \langle \exists k: 0 \leqslant k: b = 2^k \times B \rangle, bnd: b\} \\ \operatorname{do} b \neq B \rightarrow \\ \operatorname{if} r < b / 2 \Rightarrow q, b:=q \times 2, b / 2 \\ \mid b / 2 \leqslant r \Rightarrow q, b, r:=q \times 2 + 1, b / 2, \\ r - b / 2 \end{array}$$
find
$$\begin{array}{l} \operatorname{od} \\ \{A = q \times B + r \land 0 \leqslant r < B\} \end{array}$$

In developing such programs,

• We can introduce variables such as k, and realise that they are ghost variables and remove them later.

• Or we can have existential quantification in assertions to begin with, if you are sure that the quantified variables won't be needed.

# **Alternative Program**

Kaldewaij [Kal90] presented the following alternative. Do you prefer this program?

 $\begin{array}{l} \operatorname{\mathbf{con}} A, B: Int \left\{ 0 \leqslant A \land 0 < B \right\} \\ \operatorname{\mathbf{var}} q, r, b, k: Int \\ b, k:=B, 0 \\ \operatorname{\mathbf{do}} b \leqslant A \rightarrow b, k:=b \times 2, k+1 \operatorname{\mathbf{od}} \\ q, r:=0, A \\ \operatorname{\mathbf{do}} b \neq B \rightarrow \\ q, b, k:=q \times 2, b / 2, k-1 \\ \operatorname{\mathbf{if}} r < b \rightarrow skip \\ \mid b \leqslant r \rightarrow q, r:=q+1, r-b \\ \operatorname{\mathbf{fi}} \\ \operatorname{\mathbf{od}} \\ \left\{ A = q \times B + r \land 0 \leqslant r < B \right\} \end{array}$ 

- The program has the advantage that we do not need to have  $b \neq 2$  in the guards.
- Note what the first assignment establishes:

$$\begin{split} \{A &= q \times b + r \land 0 \leqslant r < b \land \\ 0 &\leqslant k \land b = 2^k \times B \land b \neq B \} \\ q, b, k &:= q \times 2, b / 2, k - 1 \\ \{A &= q \times b + r \land 0 \leqslant r < 2 \times b \land \\ 0 &\leqslant k \land b = 2^k \times B \} \end{split}$$

### **A Historical Note**

• The correctness of the **if** in the loop was actually a key example in Dahl [DDH72], one of the earliest book on *structured programming*:

$$\begin{array}{l} \{0 \leqslant r < b\} \\ b := b \ / \ 2 \\ \text{if } r < b \rightarrow skip \\ \mid b \leqslant r \rightarrow r := r - b \\ \text{fi} \\ \{0 \leqslant r < b\} \end{array}$$

- In Dahl [DDH72], Dijkstra needed about one page of textual proof.
- These days we can prove its correctness by routine symbolic manipulation. It shows how much symbolic reasoning has advanced since then.

# 2 Binary Search Revisited

# **Binary Search**

- Given a sorted array of N numbers and a key, either locate the position where the key resides in the array, or report that the key does not present in the array, in  $O(\log N)$  time.
- A possible spec:

 $\begin{array}{l} \mathbf{con}\ N,K: Int\ \{0 < N\} \\ \mathbf{con}\ F: \mathbf{array}\ [0..N)\ \mathbf{of}\ Int\ \{F\ ascending\} \\ \mathbf{var}\ l,r: Int \\ bsearch \\ \{F[l] = K \lor ...\} \end{array}.$ 

# 2.1 The van Gasteren-Feijen Approach

- Van Gasteren and Feijen [vGF95] pointed a surprising fact: binary search does not apply only to sorted lists!
- In fact, they believe that comparing binary search to searching for a word in a dictionary is a major educational blunder.
- Their binary search: let  $\Phi$  be a predicate on two integers with some additional constraints to be given later:

 $\begin{array}{l} \mathbf{con} \ M,N: Int \ \{M < N \land \Phi \ M \ N \land ...\} \\ \mathbf{var} \ l,r: Int \\ bsearch \\ \{M \leqslant l < N \land \Phi \ l \ (l+1)\} \end{array}.$ 

# **Invariant and Bound**

- Invariant:  $\Phi \ l \ r \land M \leqslant l < r \leqslant N$ , loop guard:  $l + 1 \neq r$ .
- Initialisation: l, r := M, N.
- Bound: r l.
- For any m such that l < m < r, we have r m < r land m - l < r - l. Therefore both l := m and r := mdecrease the bound.

#### **Constructing the Loop Body**

• For l := m we calculate.

$$\begin{array}{l} (\Phi \ l \ r \land M \leqslant l < r \leqslant N)[l \backslash m] \\ \equiv \Phi \ m \ r \land M \leqslant m < r \leqslant N \\ \Leftarrow \Phi \ m \ r \land M \leqslant l < m < r \leqslant N \end{array}.$$

- That l < m < r is our assumption. The leftover  $\Phi m r$  gives rise to a guarded command:  $\Phi m r \rightarrow l := m$ .
- The case with r := m is similar.

#### The Program Skeleton

$$\begin{array}{l} \{M < N \land \Phi \ M \ N \} \\ l, r := M, N \\ \{\Phi \ l \ r \land M \leqslant l < r \leqslant N, bnd : r - l \} \\ \text{do } l + 1 \neq r \rightarrow \\ \{\dots \land l + 2 \leqslant r \} \\ m := \text{anything s.t. } l < m < r \\ \{\dots \land l < m < r \} \\ \text{if } \Phi \ m \ r \rightarrow l := m \\ \mid \Phi \ l \ m \rightarrow r := m \\ \text{fi} \\ \text{od} \\ \{M \leqslant l < N \land \Phi \ l \ (l + 1) \} \end{array}$$

Note: m := (l + r) / 2 is a valid choice, thanks to the precondition that  $l + 2 \leq r$ .

#### Constraints on $\Phi$

- But we need the if to be total.
- Therefore we demand a constrant on  $\Phi$ :

$$\Phi \ l \ r \Rightarrow \Phi \ l \ m \lor \Phi \ m \ r, \text{ if } l < m < r.$$
 (1)

• Some  $\Phi$  satisfying (1) (for F of appropriate type):

$$- \Phi l r \equiv F[l] \neq F[r],$$
  

$$- \Phi l r \equiv F[l] < F[r],$$
  

$$- \Phi l r \equiv F[l] \leqslant A \land A \leqslant F[r]$$
  

$$- \Phi l r \equiv F[l] \times F[r] \leqslant 0,$$
  

$$- \Phi l r \equiv F[l] \lor F[r],$$
  

$$- \Phi l r \equiv \neg (Q l) \land Q r.$$

• Van Gasteren and Feijen believe that  $\Phi$  l  $r = F[l] \neq F[r]$  is a better example when explaining binary search.

# 2.2 Searching for a Key

- The case  $\Phi$  l  $r \equiv \neg$   $(Q \ l) \land Q \ r$  is worth special attention.
- Choose Q  $i \equiv K < F[i]$  for some K.
- Therefore  $\Phi \ l \ r \equiv F[l] \leqslant K < F[r]$ .
- That constitutes the binary search we wanted!
- The postcondition:  $M \leq l < N \land F[l] \leq K < F[l+1]$ .
- Note that we do *not* yet need *F* to be sorted!
- The algorithm gives you some l such that  $F[l] \leq K < F[l+1]$ . If there are more than one such l, one is returned non-deterministically.

# Sortedness

- That *F* is sorted comes in when we need to establish that there is at most one *l* satisfying the postcondition.
- That is, either F[l] = K, or  $\neg \langle \exists i : M \leq i < N : F[i] = K \rangle$ .

### The Program... Or A Part Of It

- Let  $\Phi$   $l r = F[l] \leq K < F[r]$ .
- Processing the array fragment *F* [*a*..*b*]:

$$\begin{array}{l} l,r := a,b \\ \{ \Phi \ l \ r \land a \leqslant l < r \leqslant b, bnd : r-l \} \\ \mathbf{do} \ l+1 \neq r \rightarrow \\ m := (l+r) \ / \ 2 \\ \mathbf{if} \ F[m] \leqslant K \rightarrow l := m \\ \mid K < F[m] \rightarrow r := m \\ \mathbf{fi} \\ \mathbf{od} \\ \{ a \leqslant l < b \land F[l] \leqslant K < F[l+1] \} \end{array}$$

- Note that F[a] and F[b] are never accessed.
- This program is not yet complete ....

#### Initialisation

- But wait.. to apply the algorithm to the entire array, we need the precondition  $\Phi = 0$  N, that is  $F[0] \leq$ K < F[N]. Is that true? (We don't even have F[N].)
- One can rule out cases when the precondition do not hold (and also deal with empty array). E.g.

$$\begin{array}{l} \mbox{if } 0=N\rightarrow p:=False \\ \mid \ 0$$

• where p is *True* iff. K presents in F.

# **Pseudo Elements**

- But there is a better way ... introduce two pseudo elements!
- Let  $F[-1] = -\infty$  and  $F[N] = \infty$ .
- Initially,  $\Phi(-1) N$  is satisfied.
- In the code, F[-1] and F[N] are never accessed. Therefore we do not actually have to represent them!
- We need to be careful interpreting the result, once the main loop terminates, however.

# The Program (1)

```
Let \Phi l r = F[l] \leq K < F[r].
   con N, K : Int \{0 \leq N\}
   con F : array [0..N) of Int \{F \text{ ascending } \land
      F[-1] = -\infty \land F[N] = \infty
   var l, m, r : Int
   var p:Bool
   l, r := -1, N
   \{ \Phi \ l \ r \land -1 \leqslant l < r \leqslant N, bnd : r - l \}
   do l + 1 \neq r \rightarrow
      m := (l + r) / 2
     if F[m] \leq K \rightarrow l := m
      | K < F[m] \rightarrow r := m
     fi
   od
   \{-1 \leqslant l < N \land F[l] \leqslant K < F[l+1]\}
```

# The Program (2)

$$\begin{array}{l} \{-1 \leqslant l < N \land F[l] \leqslant K < F[l+1] \} \\ \textbf{if} - 1 = l \rightarrow p := False \\ \mid 0 \leqslant l \quad \rightarrow p := F[l] = K \\ \textbf{fi} \\ \{p = \langle \exists i : 0 \leqslant i < N : F[i] = K \rangle \land \\ p \Rightarrow F[l] = K \} \end{array}$$

. . . .

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# **Alternative Program**

- Kaldewaij [Kal90, Sec. 6.3] derived an alternative program that introduces only  $F[N] = \infty$  (but not  $F[-1] = -\infty$ ), while requiring the array to be nonempty.
- · The main loop is the same. It is only post-loop interpretation that is different.

#### **Searching with Premature Return** 2.3

# A More Common Program

• Recall that Bentley [Ben86, pp. 35-36] proposed using binary search as an exercise.

· Bentley's solution can be rephrased below:

$$\begin{array}{l} l,r,p:=0,N-1,False\\ \mathbf{do}\ l\leqslant r\rightarrow\\ m:=(l+r)\ /\ 2\\ \mathbf{if}\ F[m]< K\rightarrow l:=m+1\\ |\ F[m]=k\ \rightarrow p:=True; \ break\\ |\ K< F[m]\rightarrow r:=m-1\\ \mathbf{fi}\\ \mathbf{od} \end{array}$$

# A More Common Program

I'd like to derive it, but

- it is harder to formally deal with break.
  - Still, Bentley employed a semi-formal reasoning using a loop invariant to argue for the correctness of the program.
- To relate the test F[m] < K to l := m + 1 we have to bring in the fact that F is sorted earlier.

#### Comparison

- The two programs do not solve exactly the same problem (e.g. when there are multiple *K*s in *F*).
- Is the second program quicker because it assigns land r to m + 1 and m - 1 rather than m?
  - l := m+1 because F[m] is covered in another case;
  - r := m 1 because a range is represented differently.
- Is it quicker to perform an extra test to *return* early?
  - When K is not in F, the test is wasted.
  - Rolfe [Rol97] claimed that single comparison is quicker in average.
  - Knuth [Knu97, Exercise 23, Section 6.2.1]: single comparison needs  $17.5 \lg N + 17$  instructions, double comparison needs  $18 \lg N 16$  instructions.

# References

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